

FURTHER MATHS TERM BY TERM CURRICULUM

[Specification link - Edexcel Specification: AS Further Mathematics](#)

[Specification link - Edexcel Specification: A Level Further Mathematics](#)



January 2023

YEAR 12

TERM	Teacher 1 (Further Core Mathematics) delivered via 3 x 70minute lesson per week	Teacher 2 (Decision Mathematics & Further Mechanics) delivered via 1 x 70 minute lesson per week
1	<p>FC1.1 Complex Numbers</p> <ul style="list-style-type: none"> • Solve any quadratic equation with real coefficients. • Add, subtract and multiply complex numbers in the form $x + iy$ with x and y real. • Understand and use the terms 'real part' and 'imaginary part'. • Use and interpret Argand diagrams. • Convert between the Cartesian form and the modulusargument form of a complex number. • Multiply and divide complex numbers in modulus-argument form. • Construct and interpret simple loci in the Argand diagram such as $z - a > r$ and $\arg(z - a) = \theta$. 	<p>D1.2 Algorithms on Graphs (Part 1)</p> <ul style="list-style-type: none"> • Understand what an algorithm is. • Trace an algorithm in the form of a flow chart. • Trace an algorithm given as instructions written in text. • Know how to determine the output of an algorithm and how it links to the input. • Be able to determine the order of a given algorithm and standard network problems. • Know how to apply a bubble sort algorithm to a list of numbers or words. • Know how to apply the quick sort algorithm to a list of numbers or words, clearly identifying the pivots used for each pass. • Identify the number of comparisons and swaps used in a given pass. • Identify size, efficiency and order of an algorithm and use them to make predictions. • Know how to solve bin packing problems using full bin, first fit, and first fit decreasing algorithms, and understand their strengths and weaknesses. • Know the meaning of the vocabulary used in graph theory e.g. degree of a vertex, isomorphic graphs, walks, paths and cycles. • Be familiar with different types of graph e.g. complete, planar, isomorphic, simple, connected. • Understand graphs represented in matrix form. • Be familiar with k notation. • Know the definition of a tree. • Be able to determine if a graph is Eulerian, semi-Eulerian or neither, and find Eulerian cycles.

<p>1</p>	<p>FC1.6 Matrices</p> <ul style="list-style-type: none"> • Find the dimension of a matrix. • Add and subtract matrices of the same dimension. • Multiply a matrix by a scalar. • Multiply conformable matrices. • Calculate determinants of 2×2 and 3×3 matrices. • Understand and use singular and non-singular matrices. • Know the properties of inverse matrices. • Calculate the inverse of non-singular 2×2 and 3×3 matrices. • Use matrices and their inverses to solve linear simultaneous equations, including three linear simultaneous equations in three variables. • Interpret geometrically the solution and failure of solution of three simultaneous linear equations. • Use matrices to represent 2D rotations, reflections, enlargements and translations. • Understand and use zero and identity matrices. • Use matrix products to represent combinations of transformations. • Use matrices to represent linear transformations in three dimensions. • Use inverse matrices to reverse the effect of a linear transformation. • Use the determinant of a matrix to determine the area scale factor of a transformation. • Find invariant points and lines for a linear transformation. 	<p>D1.2 Algorithms on Graphs (Part 1)</p> <ul style="list-style-type: none"> • Understand the meaning of a minimum spanning tree. • Apply Kruskal's algorithm to a network to find the minimum spanning tree. • Apply Prim's algorithm to a network to find the minimum spanning tree. • Apply Prim's algorithm to a distance matrix to find the minimum spanning tree. • Apply Dijkstra's algorithm to find the shortest path between two vertices in a network. • Trace back through a network to be able to find the route corresponding to the shortest path. • Consider modifications to an original shortest path problem, for example by dealing with multiple start points or a different end point.
<p>Assessment Point 1 A short assessment point is completed at the end of Term 1, following a short period of revision of the above topics (both the Further Core and Decision Mathematics modules).</p>		

<p>3</p>	<p>FC1.5 Transforming Polynomials</p> <ul style="list-style-type: none"> • Understand and use the relationship between roots and coefficients of polynomial equations up to quartic equations. • Form a polynomial equation whose roots are a linear transformation of the roots of a given polynomial equation (of at least cubic degree). <p>FC1.7 Proof</p> <ul style="list-style-type: none"> • Obtain a proof for the summation of a series, using induction. • Use proof by induction to prove that an expression is divisible by a certain integer. • Use mathematical induction to prove general statements involving matrix multiplication. 	<p>D1.9 Critical Path Analysis</p> <ul style="list-style-type: none"> • Model a project by an activity network from a precedence table. • Complete a precedence table from a given network. • Understand the use of dummies. • Know how to carry out a forward pass and backward pass using early and late event times. • Interpret and use dummies. • Be able to identify critical activities and critical paths. • Know how to determine the total float of activities. • Construct and interpret Gantt (cascade) charts.
<p>4</p>	<p>FC1.8 Vectors</p> <ul style="list-style-type: none"> • Know how to find the vector equation of a line in both two and three dimensions. • Understand and use the Cartesian forms of an equation of a straight line in three dimensions. • Understand and use the vector and Cartesian forms of the equation of a plane. • Find the scalar product of two vectors. • Check whether vectors are perpendicular by using the scalar product. • Use the scalar product to express the equation of a plane. • Use the scalar product to calculate the angle between two lines. • Use the scalar product to calculate the angle between two planes. • Use the scalar product to calculate the angle between a line and a plane. • Find the points of intersection of lines and planes which meet. • Calculate the perpendicular distance between two lines. • Calculate the perpendicular distance from a point to a line or to a plane. 	<p>FM1.1 Momentum & Impulse (Part 1)</p> <ul style="list-style-type: none"> • Understand the definitions, derivation, and units of momentum and impulse. • Understand what happens to the momentum of a sphere as a result of a collision. • Use the principle of conservation of momentum applied to direct collisions in 1-dimension. <p>FM1.3 Work, Energy & Power</p> <ul style="list-style-type: none"> • Understand the derivation, units and definitions of work and energy. • Define kinetic energy (KE). • Understand that work done on a body moving in a horizontal plane is the change in kinetic energy. • Understand the concept of gravitational potential energy (GPE). • Include GPE when applying the work-energy principle. • Know the conditions for conservation of mechanical energy. • Solve problems involving work and energy. • Understand that power in watts is the rate of doing work. • Calculate the power (P) of a vehicle with a tractive (driving) force F, moving with velocity v. • Use the formula $P = Fv$ in problem solving.

Assessment Point 2

A broader, practice-paper style assessment point is completed during Term 4, after most of the content for AS has been taught. This will cover a wider range of content from the Further Core 1, Decision Mathematics 1 and Further Mechanics 1 modules, and is designed to reflect the demands of the formal AS paper towards the end of the academic year.

5	FC1.4 Volumes of Revolution <ul style="list-style-type: none">• Derive formulae for and calculate volumes of revolution about both the x and y-axes.• Solve modelling problems which involve volumes of revolution.	FM1.5 Elastic Collisions in One Dimension <ul style="list-style-type: none">• Express the ‘compressibility’, ‘bounciness’ or ‘elasticity’ of an object by a value called the coefficient of restitution (e).• Know that $0 \leq e \leq 1$ [and that $e = 0$ means inelastic and $e = 1$ means perfectly elastic].• Know and be able to use Newton’s (experimental) law of restitution for direct impacts of elastic spheres.• Calculate the change in kinetic energy due to an impact.• Solve problems of the following types involving elastic impacts:<ul style="list-style-type: none">a) successive collisions between pairs of spheres (horizontal motion).b) bouncing ball (off a horizontal elastic plane).c) successive collisions including two spheres and sphere against a wall.d) determination of the number of collisions or deriving the possible range of e.
Revision for AS exams AS exams		
	Paper 1: Further Core Mathematics 1 50%, 1 hour 40 mins, 80 marks	Only Year 12 content assessed
	Paper 2: Decision Mathematics 1 & Further Mechanics 1 50%, 1 hour 40 mins, 80 marks	Only Year 12 content assessed Section A (25% of AS Level) Section B (25% of AS Level)

YEAR 13

Module 1 is taught by Teachers 1 and 2 across the Year, with particular focus through practical assessed activities.

TERM	Teacher 1 (Further Core Mathematics) delivered via 3 x 70minute lesson per week	Teacher 2 (Decision Mathematics & Further Mechanics) delivered via 1 x 70 minute lesson per week
1	<p>FC2.1 Complex Numbers</p> <ul style="list-style-type: none"> • Multiply and divide complex numbers in modulus-argument and exponential form. • Know and use cosine and sine in terms of the exponential form. • Understand, remember and be able to use de Moivre's theorem: $z^n = r^n e^{in\theta} = r^n(\sin n\theta + i\cos n\theta)$. • Derive multiple angle formulae/expressions e.g. $\cos 3\theta$ in terms of powers of $\cos \theta$, and $\sin^3 \theta$ in terms of multiple angles of $\sin \theta$. • Apply de Moivre's theorem to sum a geometric series. • Know how to solve completely equations of the form $z^n - a - ib = 0$, giving special attention to cases where $a = 1, b = 0$. <p>FC2.5 Hyperbolic Functions</p> <ul style="list-style-type: none"> • Know the definitions of $\sinh x$, $\cosh x$ and $\tanh x$ including their domains and ranges. • Sketch graphs of the hyperbolic functions. • Differentiate and integrate the hyperbolic functions and know the standard results. • Understand and be able to use the inverse hyperbolic functions including domains and ranges. • Derive, use and know the logarithmic forms of the inverse hyperbolic functions. 	<p>D1.3 The Planarity Algorithm</p> <ul style="list-style-type: none"> • Apply the planarity algorithm for planar graphs. • Determine if a graph contains a Hamiltonian cycle. <p>D1.5 Route Inspection</p> <ul style="list-style-type: none"> • Determine whether a graph is traversable. • Apply an algorithm to solve the route inspection problem; • Find a route by inspection. • Understand the importance of the order of vertices of the graph in finding a route.
<p>Assessment Point 1 A practice-paper style assessment point is completed at the start of Term 2. This includes contents from the Further Core 1 and Decision Mathematics 1 modules, as well as the Further Core 2 content covered during Term 1.</p>		

<p>2</p>	<p>FC2.4 Polar Coordinates</p> <ul style="list-style-type: none"> • Understand and be able to use polar coordinates and be able to convert between polar and Cartesian coordinates. • Know how to sketch standard polar curves. • Find tangents parallel and perpendicular to the initial line. • Find (compound) areas under polar graphs using the $\frac{1}{2} \int r^2 d\theta$ formula “r”$d\theta$. <p>FC2.2 Series</p> <ul style="list-style-type: none"> • Use the method of differences to sum simple finite series. • Find and use higher derivatives of functions. • Know how to express functions as an infinite series in ascending powers using Maclaurin’s expansion. • Find the series expansion of composite functions. 	<p>D1.6 The Travelling Salesperson Problem</p> <ul style="list-style-type: none"> • Understand the travelling salesman problem and that there is no simple algorithm to solve it for complex networks. • Use the nearest neighbour algorithm to find upper bounds for the problem. • Find lower bounds for a problem. • Understand that not all upper and lower bounds give a solution to the problem. • Know how to identify the best upper and lower bounds. • Solve the travelling salesman problem and interpret this solution in the context of the problem. <p>D1.8 The Simplex Algorithm</p> <ul style="list-style-type: none"> • Understand and use slack, surplus and artificial variables. • Use slack variables to write inequality constraints as equations. • Know how to rewrite LP problems so that each equation contains all the variables x, y, s, and t. • Put the information in an initial tableau. • Find the pivot and use it to form a new tableau. • Identify if a tableau satisfies the optimality condition. • Know how to use slack and surplus variables. • Understand and be able to use artificial variables. • Use the two-stage simplex algorithm. • Use the Big-M method. • Relate the solution to the original problem.
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<p>3</p>	<p>FC2.3 Further Calculus</p> <ul style="list-style-type: none"> • Know how to deal with infinity as a limit of a definite integral. • Integrate functions across limits which include values when the function is undefined i.e. deal with discontinuous integrands. • Understand and be able to evaluate the mean value of a function. • Integrate functions which can be split into partial fractions up to denominators with quadratic factors. • Differentiate inverse trigonometric functions such as $\arctan x$. • Know how to integrate functions of the form $(a^2 - x^2)^n$ and $(a^2 + x^2)^n$ and be able to choose trigonometric substitutions to integrate associated functions. • Derive formulae for and calculate volumes of revolution about both the x and y-axes. • Find volumes of revolution for functions given in parametric form. <p>FC2.6 Differential Equations</p> <ul style="list-style-type: none"> • Identify the form of first order differential equations that can be solved by an integrating factor and carry out the solution. • Find general and particular solutions of differential equations of this form. • Solve second order differential equations of the form $y'' + ay' + by = f(x)$ where $f(x)$ is a polynomial, exponential or trigonometric function. • Find general and particular solutions of second order differential equations of this form. • Use differential equations in modelling in kinematics and in other contexts. • Solve the equation for simple harmonic motion $\ddot{x} = -\omega^2 x$ and relate the solution to the motion. • Model damped oscillations using second order differential equations and interpret their solutions. 	<p>D1.10 Resource Histograms</p> <ul style="list-style-type: none"> • Draw and interpret resource histograms. • Level resource histograms. • Construct a scheduling diagram. • Interpret and modify schedules to meet requirements. <p>FM1.2 Momentum & Impulse (Part 2)</p> <ul style="list-style-type: none"> • Extend the definition of linear momentum and impulse to 2-D using vectors. • Use the impulse-momentum principle in vector form, i.e. $I = mv - mu$. <p>FM1.4 Elastic Strings & Springs</p> <ul style="list-style-type: none"> • Investigate the ability of strings to stretch and springs to stretch and compress. • Define the modulus of elasticity (λ), natural length (a) and extension (x). • Use the above definitions to work out the tension in a stretched string or a stretched/compressed spring <p style="text-align: center;">$T = \frac{\lambda x}{a}$</p> <p>i.e. use Hooke's Law, $T = \frac{\lambda x}{a}$.</p> <ul style="list-style-type: none"> • Derive the elastic potential energy (EPE) from Hooke's Law by applying the work done in stretching a string/spring, <p style="text-align: center;">$EPE = \frac{1}{2} \lambda \frac{x^2}{a}$</p> <p>i.e. $EPE = \frac{1}{2} T x$.</p> <ul style="list-style-type: none"> • Calculate the tension in a string or spring when a system is held in equilibrium. • Include EPE when using the work-energy principle. • Know the conditions for conservation of mechanical energy. • Solve string/spring problems involving work and energy (i.e. KE, GPE and EPE).
<p>Assessment Point 2 (Mock)</p> <p>Students sit a mock paper at the end of Term 3 which covers most of the AS Level and A Level content.</p>		

4	Revision for final exams	<p>FM1.6 Elastic Collisions in Two Dimensions</p> <ul style="list-style-type: none"> • Understand that during an impact the impulse acts perpendicularly to the surface through the centre of the sphere. • Apply Newton's (experimental) law of restitution in the direction of the impulse. • Appreciate that perpendicular to the impulse, the velocity component does not change. • Understand and be able to calculate an angle of deflection. • Calculate the kinetic energy 'lost' in an impact. • Work in speeds and angles or in velocity vectors (i, j). • Understand that, during a collision between two smooth spheres, total momentum is conserved and the impulse acts in the direction of the line of centres. • Apply Newton's (experimental) law of restitution in the direction of the line of centres. • Appreciate that perpendicular to the line of centres, velocity components do not change. • Understand and be able to calculate an angle of deflection. • Calculate the kinetic energy 'lost' in a collision. • Work in speeds and angles or in velocity vectors (i, j).
5	Revision for final exams	
6	<p>Paper 1: Further Core Mathematics 25%, 1 hour 30 mins, 75 marks</p>	Any pure content can be assessed on either paper
	<p>Paper 2: Further Core Mathematics 25%, 1 hour 30 mins , 75 marks</p>	
	<p>Paper 3: Decision Mathematics 1 25%, 1 hour 30 mins, 75 marks</p>	
	<p>Paper 4: Further Mechanics 1 25%, 1 hour 30 mins, 75 marks</p>	